

## Data Element

<b>Name</b>	SCP-LoggedEventType
<b>Identifier</b>	tspdd 108
<b>Purpose</b>	Identify the type of a signal priority related event in an event log.

### Usage

DRAFT

### Definition

```

ENUMERATED
{
priority-request (1),      --priority request message to PRS
priority-request-ack (2), --to PRG
priority-update (3),      --priority update message to PRS
priority-update-ack (4),  --to PRG
priority-control (5),     --priority status control message to PRS
priority-control-ack (6), --to PRG
priority-buffer (7),      --priority status buffer message to PRS
priority-buffer-response (8), --to PRG
priority-cancel (9),      --priority request cancellation message to PRS
priority-cancel-ack (10), --to PRG
priority-clear (11),      --priority request clear message to PRS
priority-clear-ack (12),  --to PRG
priority-request-grant (21),
priority-request-deny (22),
priority-request-downgrade (23),
priority-request-preempted (24),
priority-request-cleared (25), --from table
green-phase-begin (26),
green-phase-end (27),
vehicle-arrival-at-queue (51),
vehicle-arrival-at-stopbar (52),
vehicle-clear-intersection (53),
vehicle-delay-detected (54),
vehicle-diversion-detected (55)
}

```

## ***Data Element***

<b><i>Name</i></b>	SCP-NTCIP-1211-Scenario
<b><i>Identifier</i></b>	tspdd 101
<b><i>Purpose</i></b>	Define which of four NTCIP 1211 defined scenarios is to be used at a given intersection.

### ***Usage***

DRAFT

### ***Definition***

```
ENUMERATED
{
scenario1 (1),--per NTCIP 1211
scenario2 (2),--per NTCIP 1211
scenario3 (3),--per NTCIP 1211
scenario4 (4),--message based per NTCIP 1211
scenario5 (5),
scenario4 optical (104)
}
```

## ***Data Element***

<b><i>Name</i></b>	SCP-PriorityRequestID
<b><i>Identifier</i></b>	tspdd 104
<b><i>Purpose</i></b>	Provide a unique identifier (from the PRG's perspective) for a signal priority request.

***Usage*** This data element corresponds exactly to the "Priority Request ID" defined in NTCIP 1211.

***Definition*** UBYTE

## ***Data Element***

<b><i>Name</i></b>	SCP-PriorityStrategyNumber
<b><i>Identifier</i></b>	tspdd 100
<b><i>Purpose</i></b>	Provide a locally defined 1-byte priority strategy variable, consistent with the strategy number definition of NTCIP 1211.

### ***Usage***

DRAFT

***Definition*** UBYTE

## ***Data Element***

<b><i>Name</i></b>	SCP-StatusCodeForPRG
<b><i>Identifier</i></b>	tspdd 111
<b><i>Purpose</i></b>	Provide the status code for a priority request from the PRS to the PRG.

***Usage*** This data element is intended to exactly match the data element "PriorityRequestStatusCodeForPRG" defined in NTCIP 1211.

***Definition*** UBYTE

## ***Data Element***

<b><i>Name</i></b>	SCP-StatusForPRG
<b><i>Identifier</i></b>	tspdd 110
<b><i>Purpose</i></b>	Provide the status of a table entry for a priority request from the PRS to the PRG.

***Usage*** This data element is intended to exactly match the data element "PriorityRequestStatusForPRG" defined in NTCIP 1211.

***Definition*** UBYTE

## ***Data Element***

<b><i>Name</i></b>	SCP-TimeInterval
<b><i>Identifier</i></b>	tspdd 105
<b><i>Purpose</i></b>	Define a time interval in seconds into the future at which a signal priority event (e.g. arrival at the stop bar, or clearance of the intersection) is predicted to occur.

<b><i>Usage</i></b>	This data element corresponds exactly to either of the elements "PriorityRequestTimeOfServiceDesired" or "PriorityRequestTimeOfEstimatedDeparture". Defined in NTCIP 1211.
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<b><i>Definition</i></b>	USHORT
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## ***Data Element***

<b><i>Name</i></b>	SCP-VehicleClassLevel
<b><i>Identifier</i></b>	tspdd 119
<b><i>Purpose</i></b>	Identify a vehicle level within a class to a Priority Request Server as part of a signal priority request.

***Usage*** This data element corresponds exactly to "PriorityRequestVehicleClassLevel" as defined in NTCIP 1211. The allowed range of values is 1..10.

***Definition*** UBYTE



## ***Data Element***

<b><i>Name</i></b>	SCP-VehicleClassType
<b><i>Identifier</i></b>	tspdd 106
<b><i>Purpose</i></b>	Identify a vehicle class to a Priority Request Server as part of a signal priority request.

***Usage*** This data element corresponds exactly to "PriorityRequestVehicleClassType" as defined in NTCIP 1211. The allowed range of values is 1..10.

***Definition*** UBYTE

## ***Data Element***

<b><i>Name</i></b>	TSP-ApproachID
<b><i>Identifier</i></b>	tspdd 116
<b><i>Purpose</i></b>	A unique identifier for an approach to a specified intersection.

***Usage***                    The value zero is used to signify all approaches.

DRAFT

***Definition***                IDENS

## ***Data Element***

<b><i>Name</i></b>	TSP-ArrivalTime
<b><i>Identifier</i></b>	tspdd 117
<b><i>Purpose</i></b>	Define the schedule, expected, earliest, or latest arrival time of a PTV at an intersection.

### ***Usage***

DRAFT

***Definition***      SCHTIME

## ***Data Element***

<b><i>Name</i></b>	TSP-BoundaryID
<b><i>Identifier</i></b>	tspdd 115
<b><i>Purpose</i></b>	A unique numeric identifier for a geographical boundary related to an intersection for signal priority usage.

### ***Usage***

DRAFT

***Definition*** IDENS

## ***Data Element***

<b><i>Name</i></b>	TSP-DropAddr
<b><i>Identifier</i></b>	tspdd 114
<b><i>Purpose</i></b>	A layer-2 address for an intersection on a multidrop communications path

### ***Usage***

DRAFT

***Definition*** UBYTE

## Data Element

<b>Name</b>	TSP-IntersectionPath
<b>Identifier</b>	tspdd 109
<b>Purpose</b>	Used to identify the path that a transit vehicle wants to follow through an intersection.

**Usage**

In NTCIP Scenario #3, the TMC requires this information from the transit control center to generate priority requests on behalf of the transit fleet. Value 0 is reserved. Values 1-8 are "normal" and diagonal moves. Values 9-100 are reserved. Values 101-200 are for local use. Values 201-255 are reserved.

**Definition**

```

ENUMERATED
{
straight-thru (1), --approximately 0 degree turn
right-turn (2),   --approximately +90 degree turn
left-turn (3),   --approximately -90 degree turn
u-turn (4),      --approximately 180 degree turn
diag-right-turn (5), --approximately +45 degree turn
diag-left-turn (6),--approximately -45 degree turn
sharp-right-turn (7), --approximately +135 degree turn
sharp-left-turn (8), --approximately -135 degree turn
}

```

## ***Data Element***

<b><i>Name</i></b>	TSP-ModemPhoneNum
<b><i>Identifier</i></b>	tspdd 112
<b><i>Purpose</i></b>	The telephone number of a modem to access an intersection controller.

### ***Usage***

DRAFT

***Definition*** TELEPHONE

## ***Data Element***

<b><i>Name</i></b>	TSP-TMS-IntersectionID
<b><i>Identifier</i></b>	tspdd 113
<b><i>Purpose</i></b>	A Unique numeric identifier for an intersection.

### ***Usage***

DRAFT

<b><i>Definition</i></b>	IDENL
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## ***Data Frame***

<i><b>Name</b></i>	SCPAApproachAbandoned
<i><b>Identifier</b></i>	tsp 1007
<i><b>Purpose</b></i>	This frame provides information about a vehicle that was approaching an intersection as a signal priority generation candidate, but has now diverted, stopped, or otherwise abandoned its approach to the intersection.

### ***Usage***

DRAFT

### ***Definition***

```

SEQUENCE {
  vehicle          CPT-VIN,
  intersection     TMDD.Intersection-identifier,
  time-abandoned  CPT-DateTime          OPTIONAL
}

```

## Data Frame

<b>Name</b>	SCPIntersectionPass
<b>Identifier</b>	tsp 1001
<b>Purpose</b>	Provide the information required for the onboard Priority Request Generator to process a passage through an intersection as part of a pattern.

### Usage

The intersection-id field optionally allows a TMDD-compatible intersection identifier to be associated with the intersection. The intersection-address, and intersection-port fields optionally allow communications address information to be conveyed. The approach-direction and depart-direction provide optional information which may assist the PRG in accurately determining when the vehicle is approaching the stop bar, and clears the intersection. The decision-distance field is used to override the default decision distance (at which a priority request decision is made) for this intersection only. The scenario-number field indicates whether the PRG communicates with the PRS: directly (4), through the control center (1), or not at all (2 or 3). The strategies field contains the available priority strategies for this intersection, and the criteria that must be met to request each strategy. The clear-required field indicates whether the PRG should explicitly send a priority clear (TRUE), or allow the PRS to delete the priority request based on a timeout (FALSE).

### Definition

```
SEQUENCE {
intersection-address      CPT-IP-Address           OPTIONAL,
intersection-port        CPT-UDP-TCP-PortNumber  OPTIONAL,
stop-bar-location        LRMS.GeoLocation,
approach-direction       SP-AngularDirection     OPTIONAL,
depart-direction         SP-AngularDirection     OPTIONAL,
decision-distance        SP-DistanceInMeters     OPTIONAL,
clear-required           CPT-Boolean,
scenario-number          SCP-NTCIP-1211-Scenario,
strategies               SEQUENCE (SIZE(1..20)) OF SCPStrategyCriteria
}
```

## ***Data Frame***

<b><i>Name</i></b>	SCPIntersectionPattern
<b><i>Identifier</i></b>	tsp 1000
<b><i>Purpose</i></b>	Provide the information required to implement signal priority for the equipped intersections in a pattern.

<b><i>Usage</i></b>	<p style="text-align: center; opacity: 0.5; font-size: 2em; font-weight: bold;">DRAFT</p> <p>If the pattern includes more than one pass through the same intersection, there must be two entries in the intersections field. Intersections must be included in the order in which they are traversed when the bus executes the pattern.</p>
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<b><i>Definition</i></b>	<pre> SEQUENCE {   pattern-id      SCH-PatternID,   intersections   SEQUENCE (SIZE(1..1000)) OF SCPIntersectionPass } </pre>
--------------------------	--

## Data Frame

<b>Name</b>	SCPStrategyCriteria
<b>Identifier</b>	tsp 1002
<b>Purpose</b>	Define a signal priority strategy available for use at an intersection, and the criteria that must be met for that strategy to be requested.

### Usage

The strategy in this frame may be requested at the intersection specified in the ScpIntersectionPass frame, based on this frame only if all criteria fields that are present are satisfied. It is an error for the criteria to be defined in such a way that more than one set of criteria is met on any single pass through an intersection. Any criteria fields that are not included in the frame, are not considered in determining whether the strategy may be requested.

The earliest-time-of-day, and latest-time-of-day fields, if present, limit the PRG to requesting this strategy only if the current time is within the specified interval. The day-types-allowed field, if present, constrains the PRG to request the strategy only if the current day type matches an item in the list. The minimum-passengers-onboard, and maximum-passengers-onboard field constrain the PRG to request the strategy only if the current passenger loading is within the specified range.

The trip-types-allowed field, if present, constrains the PRG to request the strategy only if the vehicle's current status matches one of the items in the list. The earliest-adherence-allowed field if present precludes the PRG from requesting the strategy if the vehicle is earlier than the indicated amount. The latest-adherence-allowed field, if present, precludes the PRG from requesting the strategy if the vehicle is later than the indicated amount. Note that a strategy can be assigned for use by a supervisory vehicle by including the vehicle class field with the appropriate supervisory vehicle class, and omitting all other optional fields in an instance of this frame.

### Definition

```
SEQUENCE {
strategy-number          SCP-PriorityStrategyNumber,
earliest-time-of-day     SCH-TimeBegin                OPTIONAL,
latest-time-of-day      SCH-TimeEnd                  OPTIONAL,
day-types-allowed        SEQUENCE (SIZE(1..20)) OF SCH-DayType  OPTIONAL,
minimum-passengers-onboard OB-J1587-PassengerCounterPatronCount  OPTIONAL,
maximum-passengers-onboard OB-J1587-PassengerCounterPatronCount  OPTIONAL,
trip-types-allowed       SEQUENCE (SIZE(1..20)) OF SCH-TripType  OPTIONAL,
earliest-adherence-allowed OB-ScheduleAdherenceOffset          OPTIONAL,
latest-adherence-allowed OB-ScheduleAdherenceOffset          OPTIONAL,
vehicle-class            SEQUENCE (SIZE(1..10)) OF SCP-VehicleClassType  OPTIONAL
}
```

## ***Data Frame***

<i><b>Name</b></i>	TSPAllowedIntersection
<i><b>Identifier</b></i>	tsp 1010
<i><b>Purpose</b></i>	Define an allowed intersection, approach, boundary combination for a specified TSP strategy.

***Usage*** If the "allowed-approaches" field is missing then all approaches are allowed. Either intersection-tsp or intersection-tmdd must be present.

***Definition***

```

SEQUENCE {
intersection-tsp      TSP-TMS-IntersectionID           OPTIONAL,
intersection-tmdd    TMDD.Intersection-identifier      OPTIONAL,
allowed-approaches  SEQUENCE (SIZE(1..10)) OF TSP-ApproachID  OPTIONAL
}

```

## ***Data Frame***

<b><i>Name</i></b>	TSPBoundaryEntry
<b><i>Identifier</i></b>	tsp 1012
<b><i>Purpose</i></b>	Provide a boundary definition. The boundary is used to specify limits within which signal priority is allowed for an intersection or group of intersections.

### ***Usage***

DRAFT

### ***Definition***

```
SEQUENCE {  
  boundaryID      TSP-BoundaryID,  
  boundaryPolygon LRMS.PolygonType  
}
```

## ***Data Frame***

<i><b>Name</b></i>	TSPEventLogEntry
<i><b>Identifier</b></i>	tsp 1005
<i><b>Purpose</b></i>	Convey information about a signal priority logged event.

### ***Usage***

This data frame is used for both PRS and PRG transfers of signal priority event history to the transit control center, or data repository. Optional fields are included if applicable to the event type specified in the frame. Normally the PRS will use the strategy employed field and not the actual-wait-time field, and vice versa for the PRG.

### ***Definition***

SEQUENCE {		
event-type	SCP-LoggedEventType,	
event-time	CPT-DateTime,	
intersection-tsp	TSP-TMS-IntersectionID	OPTIONAL,
intersection-tmdd	TMDD.Intersection-identifier	OPTIONAL,
requestID	SCP-PriorityRequestID	OPTIONAL,
vehicleID	CPT-VIN	OPTIONAL,
vehicleClassType	SCP-VehicleClassType	OPTIONAL,
serviceStrategyNumber	SCP-PriorityStrategyNumber	OPTIONAL,
timeOfServiceDesired	SCP-TimeInterval	OPTIONAL,
timeOfEstimatedDeparture	SCP-TimeInterval	OPTIONAL,
preemption-vehicle	CPT-VIN	OPTIONAL,
actual-wait-time	SCP-TimeInterval	OPTIONAL,
strategyEmployed	SCP-PriorityStrategyNumber	OPTIONAL
}		

## ***Data Frame***

<b><i>Name</i></b>	TSPIntersectionEntry
<b><i>Identifier</i></b>	tsp 1008
<b><i>Purpose</i></b>	Provide intersection information in the data load for a PRG.

### ***Usage***

DRAFT

### ***Definition***

```

SEQUENCE {
intersection-tsp          TSP-TMS-IntersectionID          OPTIONAL,
intersection-tmdd        TMDD.Intersection-identifier  OPTIONAL,
boundaryID               TSP-BoundaryID,
intersectionIP           CPT-IP-Address                OPTIONAL,
intersectionPort         CPT-UDP-TCP-PortNumber        OPTIONAL,
intersectionModem        TSP-ModemPhoneNum             OPTIONAL,
intersectionDropAddr     TSP-DropAddr                   OPTIONAL,
intersection-approaches SEQUENCE (SIZE(1..10))OF TSPTmsIntersectionApproach
}

```



## ***Data Frame***

<b><i>Name</i></b>	TSPPRGInputsCCEntry
<b><i>Identifier</i></b>	tsp 1014
<b><i>Purpose</i></b>	Provides a single PRGInputs set for a fixed PRG.

### ***Usage***

DRAFT

### ***Definition***

```
SEQUENCE {  
  status  
  vehicle  
  block  
  intersectionParam  
}  
TSPStatus,  
CPT-VIN,  
SCH-BlockID,  
TSPTmsIntersectionParam
```

# Data Frame

- Name** TSPScenario5Intersection
- Identifier** Tsp 1017
- Purpose** Provide information about a scenario 5 equipped intersection to the VLU.

## Usage

DRAFT

## Definition

SEQUENCE {		
intersectionTSP	TSP-TMS-IntersectionID	OPTIONAL,
intersectionTMDD	TMDD.Intersection-identifier	OPTIONAL,
intersection-location	LRMS.GeoLocation,	
stop-bar-locations	SEQUENCE (SIZE(1..8)) OF LRMS.GeoLocation,	
prg-address	CPT-IP-Address	OPTIONAL,
prg-port	CPT-UDP-TCP-PortNumber	OPTIONAL
}		

## ***Data Frame***

<b><i>Name</i></b>	TSPScheduleEntry
<b><i>Identifier</i></b>	tsp 1011
<b><i>Purpose</i></b>	Provide information about a PTV's schedule approach to an intersection.

***Usage*** If scheduledArrival is not present, then the agency does not schedule individual intersection arrival times.

***Definition***

```
SEQUENCE {  
  boundaryID      TSP-BoundaryID,  
  boundaryPolygon LRMS.PolygonType  
}
```

## ***Data Frame***

<b><i>Name</i></b>	TSPStatus
<b><i>Identifier</i></b>	tsp 1013
<b><i>Purpose</i></b>	Near-real-time operating status of a PTV input to a PRG.

***Usage*** Negative adherence offset signifies early. The doorStatusOpen field signifies at least one door is open if true. The requestCancel field signifies that any previous request should be cancelled if true.

***Definition***

SEQUENCE {	
scheduleDeviation	OB-ScheduleAdherenceOffset,
currentLocation	SPGeoDynamicPoint,
currentTime	CPT-DateTime,
doorStatusOpen	CPT-Boolean,
requestCancel	CPT-Boolean
}	

## Data Frame

<b>Name</b>	TSPStrategyEntry
<b>Identifier</b>	tsp 1009
<b>Purpose</b>	Define the constraints that must be met to use a specific TSP strategy for an intersection or group of intersections.

### Usage

Absent fields do not constrain the use of the strategy. For example if the "strategyTimeBegin" field absent then there is no earliest time to implement the strategy. If there are no "allowed-intersections" then all intersection are allowed.

### Definition

```

SEQUENCE {
resultantStrategyID      SCP-PriorityStrategyNumber,
resultantClassType      SCP-VehicleClassType,
resultantClassLevel     SCP-VehicleClassLevel,
strategyTimeBegin      TSP-ArrivalTime                OPTIONAL,
strategyTimeEnd        TSP-ArrivalTime                OPTIONAL,
schLateMinimum         OB-ScheduleAdherenceOffset    OPTIONAL,
schLateMaximum        OB-ScheduleAdherenceOffset    OPTIONAL,
schRecoveryMinimum     OB-ScheduleAdherenceOffset    OPTIONAL,
prgLoadMinimum        OB-J1587-PassengerCounterPatronCount OPTIONAL,
travelPath             TSP-IntersectionPath          OPTIONAL,
allowed-boundaries     SEQUENCE (SIZE(1..10000)) OF TSP-BoundaryID,
allowed-intersections  SEQUENCE (SIZE(1..10000)) OF TSPAllowedIntersection OPTIONAL
}

```

## Data Frame

<b>Name</b>	TSPtmsIntersectionApproach
<b>Identifier</b>	TSP 1016
<b>Purpose</b>	Define parameters related to an approach to an intersection by a PTV.

### Usage

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### Definition

```

SEQUENCE {
  approachID          TSP-ApproachID,
  approachAngle       SP-AngularDirection,
  departAngle         SP-AngularDirection,
  travelPath          TSP-IntersectionPath,
  stopBarLocation     LRMS.GeoLocation          OPTIONAL,
  requestBeginLocation LRMS.GeoLocation          OPTIONAL,
  requestEndLocation  LRMS.GeoLocation          OPTIONAL,
  requestCancelLocation LRMS.GeoLocation          OPTIONAL,
  allowedStrategies   SEQUENCE (SIZE(1..10)) OF SCP-PriorityStrategyNumber
}

```

## ***Data Frame***

<i><b>Name</b></i>	TSPTmsIntersectionParam
<i><b>Identifier</b></i>	tsp 1015
<i><b>Purpose</b></i>	Convey information about an itersection for use by PRG.

***Usage*** At least one of te intersection-tsp or intersection-tmdd fields must be present.

***Definition***

SEQUENCE {		
intersection-tsp	TSP-TMS-IntersectionID	OPTIONAL,
intersection-tmdd	TMDD.Intersection-identifier	OPTIONAL,
boundary	TSP-BoundaryID	OPTIONAL,
intersectionIP	CPT-IP-Address	OPTIONAL,
intersectionPort	CPT-UDP-TCP-PortNumber	OPTIONAL,
intersectionModem	TSP-ModemPhoneNum	OPTIONAL,
intersectionDropAddr	TSP-DropAddr	OPTIONAL,
approaches	SEQUENCE (SIZE(1..25)) OF TSPTmsIntersectionApproach	OPTIONAL
}		

# Message

<b>Name</b>	ScpEventLog
<b>Identifier</b>	Tsp 2014
<b>Purpose</b>	Provide an event log for signal priority requests from the Traffic Management Center to the transit Control Center or data repository.

## Usage

The begin-time, and end-time fields specify the time interval for which logged information is provided. The intersections-list field or the intersection tsp field specifies the list of intersections for which log information is provided. If there is no log data for the specified interval, the intersection-list, intersection-tsp, and event-log fields are omitted.

## Definition

```

SEQUENCE {
subscriptionInfo      CPTSubscriptionHeader,
begin-time            CPT-DateTime,
end-time              CPT-DateTime,
intersections-tsp     SEQUENCE(SIZE(1..100000)) OF TSP-TMS-IntersectionID,
intersections-tmdd    SEQUENCE(SIZE(1..100000)) OF TMDD.Intersection-identifier OPTIONAL,
intersection-ids      SEQUENCE(SIZE(1..100000)) OF TSP-TMS-IntersectionID OPTIONAL,
event-log             SEQUENCE(SIZE(1..100000)) OF TSPEventLogEntry
}

```



## Message

<b>Name</b>	ScpEventLogSub
<b>Identifier</b>	Tsp 2015
<b>Purpose</b>	Request an event log for signal priority events from the Traffic Management Center.

### Usage

The begin-time and end-time fields are used to specify the time interval for which history data is requested. The intersection-tsp, or intersection-tmdd field specifies the list of intersections for which history data is requested, omission of this field signifies "all intersections".

### Definition

```

SEQUENCE {
  subscriptionInfo      CPTSubscriptionHeader,
  begin-time            CPT-DateTime,
  end-time              CPT-DateTime,
  intersections-tsp    SEQUENCE(SIZE(1..100000))OF TSP-TMS-IntersectionID  OPTIONAL,
  intersections-tmdd   SEQUENCE(SIZE(1..100000))OF TMDD.Intersection-identifier  OPTIONAL
}

```

# Message

<b>Name</b>	ScpPriorityCancel
<b>Identifier</b>	Tsp 2002
<b>Purpose</b>	Instruct the PRS to cancel a previously requested priority request.

## Usage

For transmission to the PRS, this is an Octet Encoding Rules (OER) string of size 21. This message equates to the prgPriorityCancel defined in NTCIP 1211. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

## Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID         CPT-VIN,              --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  intersectionID     TSP-TMS-IntersectionID      OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum           OPTIONAL,
  intersectionDropAddr TSP-DropAddr              OPTIONAL,
  intersectionIP     CPT-IP-Address              OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber      OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

## Message

<b>Name</b>	ScpPriorityCancelAck
<b>Identifier</b>	Tsp 2003
<b>Purpose</b>	Acknowledge a cancellation of a priority request.

### Usage

For transmission from the PRS, this is an Octet Encoding Rules (OER) string of size 21. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

### Definition

```
SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN,             --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  intersectionID     TSP-TMS-IntersectionID    OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum        OPTIONAL,
  intersectionDropAddr TSP-DropAddr            OPTIONAL,
  intersectionIP     CPT-IP-Address           OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber  OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}
```

# Message

<b>Name</b>	ScpPriorityClear
<b>Identifier</b>	Tsp 2012
<b>Purpose</b>	Notify the PRS that the vehicle has cleared the intersection and that the priority request can be cleared from the table.

## Usage

For transmission to the PRS, this is an Octet Encoding Rules (OER) string of size 21. This message equates prgPriorityClear defined in NTCIP 1211. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

## Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID         CPT-VIN,          --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  intersectionID     TSP-TMS-IntersectionID    OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum        OPTIONAL,
  intersectionDropAddr TSP-DropAddr           OPTIONAL,
  intersectionIP     CPT-IP-Address           OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber  OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

## Message

<b>Name</b>	ScpPriorityClearAck
<b>Identifier</b>	Tsp 2001
<b>Purpose</b>	Acknowledge a priority clear.

### Usage

For transmissions from the PRS, this is an Octet encoding rules (OER) string of size 21. the optional fields are for use only between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

### Definition

```
SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN,           --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  intersectionID     TSP-TMS-IntersectionID     OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum          OPTIONAL,
  intersectionDropAddr TSP-DropAddr              OPTIONAL,
  intersectionIP     CPT-IP-Address              OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber     OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}
```

# Message

<b>Name</b>	ScpPriorityRequest
<b>Identifier</b>	Tsp 2011
<b>Purpose</b>	Request priority treatment for a transit vehicle from a traffic signal.

## Usage

For transmission to the PRS this is an Octet Encoding Rules (OER) string of size 25. The requestID field is assigned by the PRG. This message equates to the prgPriorityRequest defined in NTCIP 1211.

## Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID         CPT-VIN,             --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  timeOfServiceDesired SCP-TimeInterval, --2octets
  timeOfEstimatedDeparture SCP-TimeInterval, --2octets
  intersectionID     TSP-TMS-IntersectionID OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum   OPTIONAL,
  intersectionDropAddr TSP-DropAddr      OPTIONAL,
  intersectionIP     CPT-IP-Address      OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

## Message

<b>Name</b>	ScpPriorityRequestAck
<b>Identifier</b>	Tsp 2010
<b>Purpose</b>	Acknowledge a priority request

### Usage

For transmission from the PRS this is an Octet Encoding Rules (OER) string of size 25. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

### Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN,             --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  timeOfServiceDesired SCP-TimeInterval, --2octets
  timeOfEstimatedDeparture SCP-TimeInterval, --2octets
  intersectionID     TSP-TMS-IntersectionID OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum   OPTIONAL,
  intersectionDropAddr TSP-DropAddr       OPTIONAL,
  intersectionIP     CPT-IP-Address       OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

# Message

<b>Name</b>	ScpPriorityUpdate
<b>Identifier</b>	Tsp 2009
<b>Purpose</b>	Request a modification to a previously sent priority request.

## Usage

For transmission to the PRS, this is an Octet Encoding Rules (OER) string of size 25. This message equates to the prgPriorityUpdate defined in NTCIP 1211. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

## Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID         CPT-VIN,             --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  timeOfServiceDesired SCP-TimeInterval, --2octets
  timeOfEstimatedDeparture SCP-TimeInterval, --2octets
  intersectionID     TSP-TMS-IntersectionID  OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum      OPTIONAL,
  intersectionDropAddr TSP-DropAddr          OPTIONAL,
  intersectionIP     CPT-IP-Address          OPTIONAL,
  intersectionPort    CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```



## Message

<b>Name</b>	ScpPriorityUpdateAck
<b>Identifier</b>	Tsp 2008
<b>Purpose</b>	Acknowledge a modification to a previously sent priority request.

### Usage

For transmission from the PRS, this is an Octet Encoding Rules (OER) string of size 25. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

### Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN,             --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  timeOfServiceDesired SCP-TimeInterval, --1octet
  timeOfEstimatedDeparture SCP-TimeInterval, --1octet
  intersectionID     TSP-TMS-IntersectionID OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum   OPTIONAL,
  intersectionDropAddr TSP-DropAddr      OPTIONAL,
  intersectionIP     CPT-IP-Address      OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

# Message

<b>Name</b>	ScpStatusBuffer
<b>Identifier</b>	Tsp 2004
<b>Purpose</b>	Provide a status buffer for the PRS to use to return the status of a previously sent priority request. This message equates to the prgPriorityStatusBuffer defined in NTCIP 1211.

## Usage

For transmission to the PRS, this is an Octet Encoding Rules (OER) string of size 23. This message equates to the prgPriorityStatusBuffer defined in NTCIP 1211. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

## Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN, --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  statusForPRG      SCP-StatusForPRG, --1octet
  statusCodeForPRG  SCP-StatusCodeForPRG, --1octet
  intersectionID     TSP-TMS-IntersectionID OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum OPTIONAL,
  intersectionDropAddr TSP-DropAddr OPTIONAL,
  intersectionIP      CPT-IP-Address OPTIONAL,
  intersectionPort    CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

## Message

<b>Name</b>	ScpStatusBufferResponse
<b>Identifier</b>	Tsp 2005
<b>Purpose</b>	Provide the status to the PRG of a previously sent priority request.

### Usage

For transmission from the PRS, this is an Octet Encoding Rules (OER) string of size 23. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

### Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN,          --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --1octet
  statusForPRG      SCP-StatusForPRG, --1octet
  statusCodeForPRG  SCP-StatusCodeForPRG, --1octet
  intersectionID     TSP-TMS-IntersectionID OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum   OPTIONAL,
  intersectionDropAddr TSP-DropAddr       OPTIONAL,
  intersectionIP      CPT-IP-Address      OPTIONAL,
  intersectionPort    CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

# Message

<b>Name</b>	ScpStatusControl
<b>Identifier</b>	Tsp 2007
<b>Purpose</b>	Request the PRS to prepare to provide status for a previously sent priority request.

## Usage

For transmission to the PRS, this is an Octet Encoding Rules (OER) string of size 21. This message equates to the prgPriorityStatusControl defined in NTCIP 1211. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

## Definition

```

SEQUENCE {
  requestID                SCP-PriorityRequestID, --1octet
  vehicleID                CPT-VIN, --17octets
  vehicleClassType        SCP-VehicleClassType, --1octet
  vehicleClassLevel       SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber   SCP-PriorityStrategyNumber, --
  1octet,intersectionAddress CPT-IP-address OPTIONAL,
  intersectionID          TSP-TMS-IntersectionID OPTIONAL,
  intersectionModem       TSP-ModemPhoneNum OPTIONAL,
  intersectionDropAddr    TSP-DropAddr OPTIONAL,
  intersectionIP          CPT-IP-Address OPTIONAL,
  intersectionPort        CPT-UDP-TCP-PortNumber OPTIONAL,
  intersectionIdentifier   TMDD.Intersection-identifier OPTIONAL
}

```

# Message

<b>Name</b>	ScpStatusControlAck
<b>Identifier</b>	Tsp 2006
<b>Purpose</b>	Acknowledge a request to prepare to provide status for a previously sent priority request.

## Usage

For transmission from the PRS this is an Octet Encoding Rules (OER) string of size 25. The optional fields are for use ONLY between the CC and the PRG in Scenario #1 only. These fields are not included in messages to and from the PRS.

## Definition

```

SEQUENCE {
  requestID          SCP-PriorityRequestID, --1octet
  vehicleID          CPT-VIN,           --17octets
  vehicleClassType  SCP-VehicleClassType, --1octet
  vehicleClassLevel SCP-VehicleClassLevel, --1octet
  serviceStrategyNumber SCP-PriorityStrategyNumber, --
  1octet,intersectionAddress CPT-IP-address      OPTIONAL,
  intersectionID     TSP-TMS-IntersectionID    OPTIONAL,
  intersectionModem  TSP-ModemPhoneNum        OPTIONAL,
  intersectionDropAddr TSP-DropAddr            OPTIONAL,
  intersectionIP     CPT-IP-Address            OPTIONAL,
  intersectionPort   CPT-UDP-TCP-PortNumber    OPTIONAL,
  intersectionIdentifier TMDD.Intersection-identifier OPTIONAL
}

```

## Message

<b>Name</b>	TspBusinessRules
<b>Identifier</b>	Tsp 2017
<b>Purpose</b>	Provide business rules associated with a PTV's use of TSP to the PRG responsible for that vehicle. The PRG may be vehicle-borne or fixed.

### Usage

DRAFT

If the PRG is not on the vehicle, the rules do not include the "schedules" field. Boundaries may be identified in either the intersections or strategies field. If not present in either location, then boundary constraints do not apply.

### Definition

```

SEQUENCE {
fileHeader  CPTLoadFileHeader,
schedules   SEQUENCE(SIZE(1..10000)) OF TSPScheduleEntry      OPTIONAL,
boundaries  SEQUENCE(SIZE(1..10000)) OF TSPBoundaryEntry      OPTIONAL,
strategies  SEQUENCE(SIZE(1..10000)) OF TSPStrategyEntry      OPTIONAL,
intersections SEQUENCE(SIZE(1..10000)) OF TSPIntersectionEntry  OPTIONAL,
type-fives  SEQUENCE (SIZE(1..10000)) OF TSPScenario5Intersection OPTIONAL
}

```

## *Message*

<b><i>Name</i></b>	TspEventLogUnload
<b><i>Identifier</i></b>	Tsp 2013
<b><i>Purpose</i></b>	Provide the history of SCP events from a PRG to the control center or data repository.

## *Usage*

DRAFT

## ***Definition***

```
SEQUENCE {  
  fileHeader      CPTUnloadFileHeader,  
  vehicleId       CPT-VehicleID,  
  event-log       SEQUENCE(SIZE(1..100000)) OF TSPEventLogEntry  
}
```

## Message

<b>Name</b>	TspPRGInputsCC
<b>Identifier</b>	Tsp 2020
<b>Purpose</b>	Used by the CAD/AVL System to provide operating status information to an external, fixed PRG.

### Usage

The only instance where the inputsToPRG field may be absent is upon receipt of a valid subscription request and there are no current inputs to provide resulting in an echo back of the request information indicating the subscription was accepted.

### Definition

```
SEQUENCE {
subscriptionInfo      CPTSubscriptionHeader,
subscriptionInfo      CPTSubscriptionHeader,
intersections-tsp     SEQUENCE(SIZE(1..100000))OF TSP-TMS-IntersectionID  OPTIONAL,
intersections-tmdd    SEQUENCE(SIZE(1..100000))OF TMDD.Intersection-identifier  OPTIONAL,
inputsToPRG           SEQUENCE (SIZE(1..500)) OF TSPPRGInputsCCEntry  OPTIONAL
}
```



# Message

<b>Name</b>	TspPRGInputsCCSub
<b>Identifier</b>	Tsp 2019
<b>Purpose</b>	Used by a fixed Priority Request Generator (PRG) external to the CAD/AVL System to subscribe to required operating information.

**Usage** Normally only one type of intersection identifier type will be included based on local requirements.

**Definition**

```

SEQUENCE {
subscriptionInfo      CPTSubscriptionHeader,
intersections-tsp     SEQUENCE(SIZE(1..100000))OF TSP-TMS-IntersectionID  OPTIONAL,
intersections-tmdd    SEQUENCE(SIZE(1..100000))OF TMDD.Intersection-identifier  OPTIONAL,
}

```

## *Message*

<b><i>Name</i></b>	TspPRGInputsPTV
<b><i>Identifier</i></b>	Tsp 2018
<b><i>Purpose</i></b>	Used by the VLU to provide operating status information to an onboard PRG, external to the VLU.

### *Usage*

DRAFT

### *Definition*

```
SEQUENCE {  
  subscriptionInfo CPTSubscriptionHeader,  
  currentStatusTSPStatus  
}
```

## *Message*

**Name** TspPRGInputsPTVSub

**Identifier** Tsp 2016

**Purpose** Used by an onboard Priority Request Generator (PRG) external to the vehicle Logic Unit to subscribe to required operating information.

## *Usage*

DRAFT

## *Definition*

```
SEQUENCE {  
  subscriptionInfo CPTSubscriptionHeader  
}
```

## Message

<b>Name</b>	TspPTVStatus
<b>Identifier</b>	Tsp 2021
<b>Purpose</b>	Send information about the state of the PTV to a wayside-based Priority Request Generator (PRG) for Scenario #5.

### Usage

DRAFT

### Definition

```

SEQUENCE {
  vehicleID          CPT-VIN,
  vehicleClassType  SCP-VehicleClassType,
  vehicleLocation   SPGeoDynamicPoint,
  scheduleStatus    PI-OffSchedule,
  intersectionTSP   TSP-TMS-IntersectionID  OPTIONAL,
  intersectionTMDD  TMDD.Intersection-identifier  OPTIONAL,
  expected-arrival-time CPT-DateTime
}

```

**Load TSP Business Rules****TCIP Dialog Definition Page 1**

**Dialog Name:** Load TSP Business Rules

**Business Area:** TSP

**Dialog Pattern:** Load

**Purpose:** Provide information to a Transit Signal Priority logical entity PTVTSP (which may include a PRG) onboard the PTV. This information is required by PTVTSP+ to generate and manage priority requests.

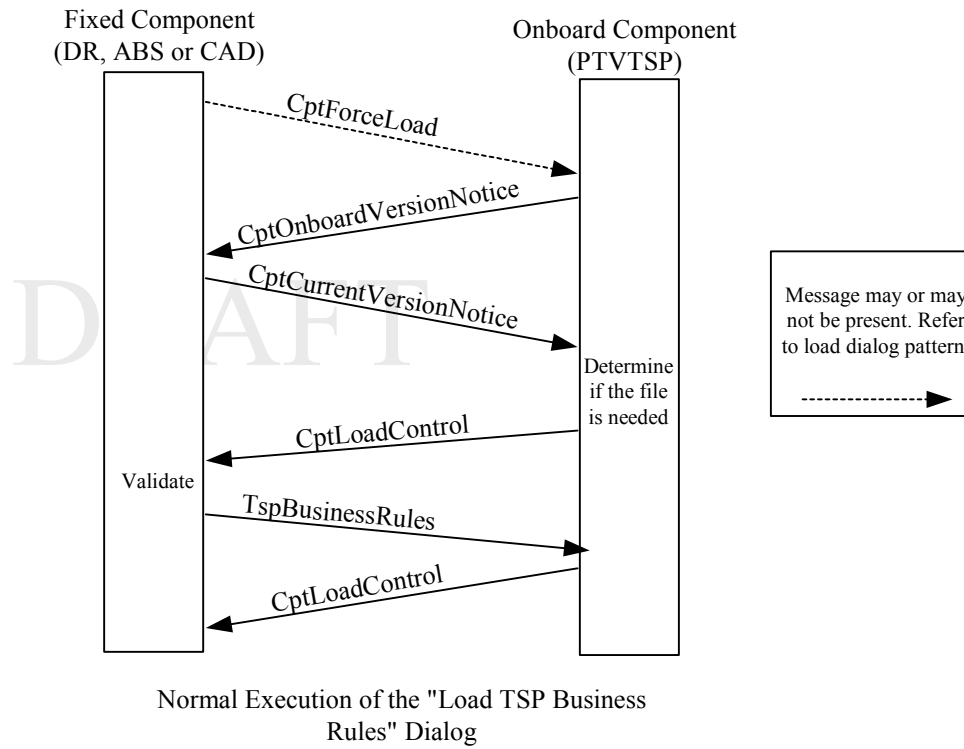
**Assumptions:**

1. The publisher component is responsible for determining the correct current version to be used by each PRG.
2. The publisher can be a Data Repository (DR), Authorized Business System (ABS), or a CAD/AVL System (CAD).
3. The subscriber can be PTV Manage Transit Signal Priority (PTVTSP).

**Narrative:**

- 1) PTVTSP triggers the dialog (based on the state of the wireless LAN, internal timers, and/or CptForceLoad message from the publisher component), by initiating a CptOnboardVersionNotice/CptCurrentVersionNotice exchange with the publisher component. PTVTSP determines if a new data load is required.
- 2) If the data on hand is current, PTVTSP sends a CptLoadControl message ending the dialog.
- 3) If the data on hand is not current, PTVTSP sends a CptLoadControl message requesting the current version.
- 4) The publisher component validates the request and terminates the dialog with a CptBadLoadRequest message (if the file request is invalid), or sends the current TSPBusinessRules message to PTVTSP.
- 5) PTVTSP receives and validates the TSPBusinessRules message and sends a CptLoadControl message terminating the dialog.

**Message Sequence Diagram Page 2**



<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> Load TSP Business Rules		
<b>Business Area:</b> Tsp		
<b>Dialog Pattern:</b> Load		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
CptForceLoad	Cpt 2011	Used by the fixed component to force the PTVTSP to initiate the load.
CptOnboardVersionNotice	Cpt 2010	Used by the PTVTSP to notify the fixed component of the ScpSignalData version number on hand.
CptCurrentVersionNotice	Cpt 2009	Used by the fixed component to notify the PTVTSP of the current version of the ScpSignalData.
CptLoadControl	Cpt 2007	PRG controls the load process with this message.
ScpSignalData	Tsp 2000	Conveys the data necessary for the PTVTSP to function.
CptBadLoadRequest	Cpt 2008	Fixed component aborts the dialog with an error notice to the PTVTSP with this message.
<b>Notes:</b>		

**Scp Priority Request Scenario 1****TCIP Dialog Definition Page 1**

**Dialog Name:** Scp Priority Request Scenario 1

**Business Area:** TSP

**Dialog Pattern:** Signal Control & Prioritization

**Purpose:** This dialog defines the generation and processing of priority requests by an onboard vehicle Priority Request Generator (PRG), with the CAD/AVL System as an intermediary according to NTCIP 1211 Scenario #1.

**Assumptions:**

- 1) The PTVTSP has already received data via the “Load TSP Business Rules” dialog.
- 2) Either the PTVTSP:
  - a. Is part of the Vehicle Logic Unit (VLU) and has access to data such as location, speed, bearing and schedule, or
  - b. Has subscriber to the necessary data from the VLU using the “Subscribe Onboard PRG Inputs” dialog.

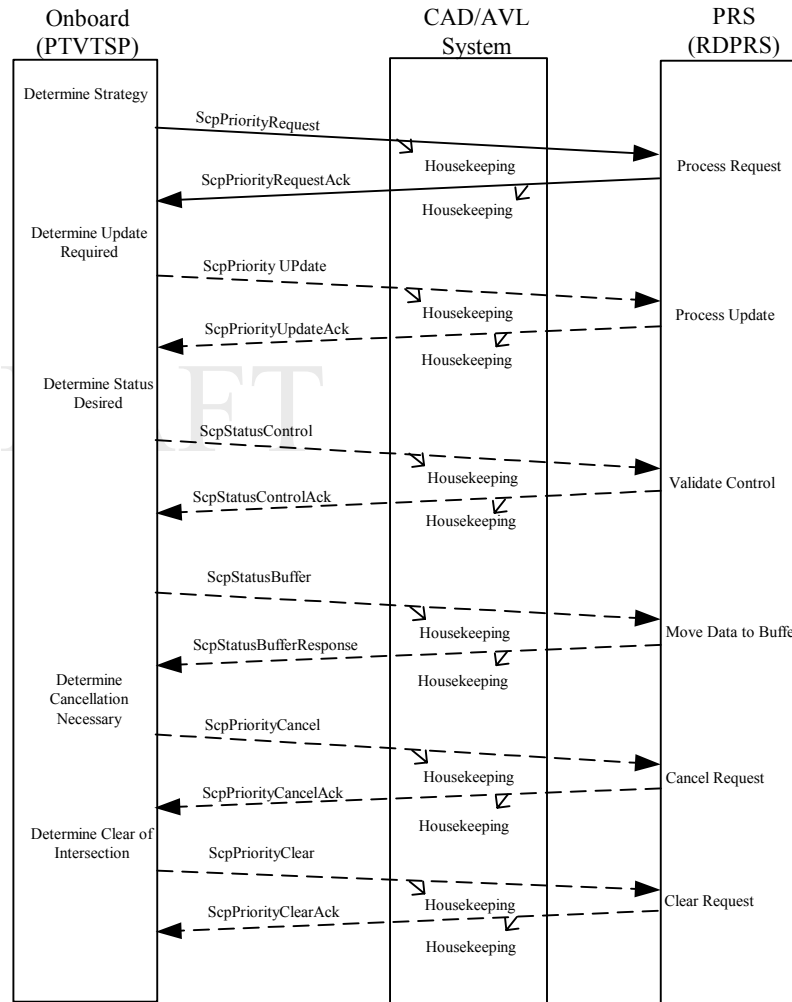
**Narrative:**

- 1) The PTVTSP determines that the vehicle is approaching an SCP-equipped Scenario #1 intersection, and that the criteria are met to initiate a priority request. The PTVTSP sends a ScpPriorityRequest message to the Priority Request Publisher (PRS) via the Control Center (CC).
  - a. The control center performs local housekeeping actions and forwards the priority request to the PRS.
  - b. The PRS validates the request and sends a ScpPriorityRequestAck to the PTVTSP via CAD.
  - c. CAD performs local housekeeping and forwards the acknowledgement to the PTVTSP.
  - d. If the acknowledgement contains an error indication, the dialog ends, otherwise the PTVTSP may optionally initiate any of items 2-5 below.
- 2) The PTVTSP determines that it requires a status update on the priority request. The PTVTSP sends a ScpStatusControl to the PRS via CAD.
  - a. CAD performs local housekeeping actions and forwards the status control to the PRS.
  - b. The PRS validates the status control and returns a ScpStatusControlAck message to the PTVTSP via CAD.
  - c. CAD performs local housekeeping and forwards the acknowledgment to the PTVTSP.
  - d. If the acknowledgement contains no error indication, the PTVTSP sends a ScpStatusBuffer to the PRS via CAD.
  - e. CAD performs local housekeeping and forwards the status buffer to the PRS.
  - f. The PRS fills the status buffer and returns it to the PTVTSP via CAD as a ScpStatusBufferResponse message.



- g. CAD performs local housekeeping and forwards the status buffer response to the PTVTSP.
- 3) The PTVTSP determines that the priority request needs to be changed as a result of changed arrival time at the intersection and/or changes to the criteria matching. The PTVTSP sends a ScpPriorityUpdate message to the PRS via CAD.
    - a. CAD performs local housekeeping actions and forwards the priority update to the PRS.
    - b. The PRS processes the update and sends a ScpPriorityUpdateAck message to the PTVTSP via CAD.
    - c. CAD performs local housekeeping actions and forwards the acknowledgement to the PTVTSP.
  - 4) The PTVTSP determines that the priority request needs to be canceled as the vehicle is not progressing towards the stop bar as planned, or has deviated from its route, or the operator manually initiates a cancel (if so equipped), or the vehicle is taken out of service, or experiences another locally defined state change requiring a cancellation. The PTVTSP sends a ScpPriorityCancel to the PRS via CAD.
    - a. CAD performs local housekeeping actions and forwards the priority cancel to the PRS.
    - b. The PRS processes the cancellation and sends a ScpPriorityCancelAck to the PTVTSP via CAD.
    - c. CAD performs local housekeeping actions and forward the acknowledgment to the PTVTSP and the dialog ends.
  - 5) The PTVTSP determines that the vehicle is clear of the intersection, and the intersection requires explicit clears. The PTVTSP sends a ScpPriorityClear message to the PRS via CAD.
    - a. CAD performs local housekeeping actions and forwards the priority clear to the PRS.
    - b. The PRS clears the request and sends a ScpPriorityClearAck to the PTVTSP via CAD.
    - c. CAD performs local housekeeping actions and forwards the acknowledgement to the PTVTSP and the dialog ends.

**Message Sequence Diagram Page 3**



Normal Execution of "Sep Priority Request Scenario 1" Dialog

<b>TCIP Dialog Definition Page 4</b>		
<b>Dialog Name:</b> Scp Priority Request Scenario 1		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Signal Control & Prioritization		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
Scp Priority Request	2011	Request a priority strategy from the PRS.
ScpPriorityRequestAck	2010	Acknowledge the priority request.
ScpPriorityUpdate	2009	Request that a previous priority request be modified.
ScpPriorityUpdateAck	2008	Acknowledge the priority update.
ScpStatusControl	2007	Request the PRS to prepare to provide status for a precious priority request.
ScpStatusControlAck	2006	Acknowledge the status control
ScpStatusBuffer	2004	Provide a buffer to obtain a priority request status
ScpStatusBufferResponse	2005	Return the status of the priority request to the PRG
ScpPriorityCancel	2002	Request the PRS to cancel a previous priority request
ScpPriorityCancelAck	2003	Acknowledge the priority cancellation
ScpPriority Clear	2012	Request the PRS to clear a completed priority request
ScpPriorityClearAck	2001	Acknowledge the priority clear.

**Notes:**

- 1) The PRG to PRS messages contain optional fields to convey intersection identifiers consistent with the Institute of Traffic Engineers Traffic Management Data Dictionary. These fields may be used by the CAD/AVL System to direct the ongoing message to the proper PRS, however the CAD/AVL System is then responsible for removing the optional fields from the message, and forwarding a message to the PRS that complies with NTCIP 1211. Similarly, an agency may elect to use TCIP narrowband encoding, or XML encoding between the PRG and the CAD/AVL System, however, the CAD/AVL System is then responsible for format the outgoing messages to the PRS consistent with NTCIP 1211, and to reformat incoming messages from the PRS consistent with its local policy. Reformatting, if required, should be considered part of the CAD/AVL System housekeeping function.
- 2) If the vehicle clears the intersection and the PTVTSP is not configured to generate a priority clear to the PRS, the dialog ends from the PTVTSP view point, and ends from the CAD/AVL System and PRS view points after a local timeout.
- 3) The criteria for determining when a priority update, status update, or priority cancel should be initiated are agency/vendor defined.

DRAFT

**Scp Priority Request Scenario 2****TCIP Dialog Definition Page 1**

**Dialog Name:** SCP Priority Request Scenario 2

**Business Area:** TSP

**Dialog Pattern:** Signal Control & Prioritization

**Purpose:** This dialog defines the generation and processing of priority requests by a transit control center based Priority Request Generator (PRG), according to NTCIP 1211 Scenario #2.

**Assumptions:**

- 1) The Control Center-based PRG has access to near-real-time vehicle information, such as vehicle location, schedule etc., either by virtue of being integrated with the CAD/AVL System, or via the Subscribe "Control Center PRG Inputs" dialog.
- 2) The PRG may be a CAD/AVL System (CAD), or other Authorized Business System (ABS).
- 3) The PRS may be Priority Request Publisher (RDPRS) (Roadside or TMC).

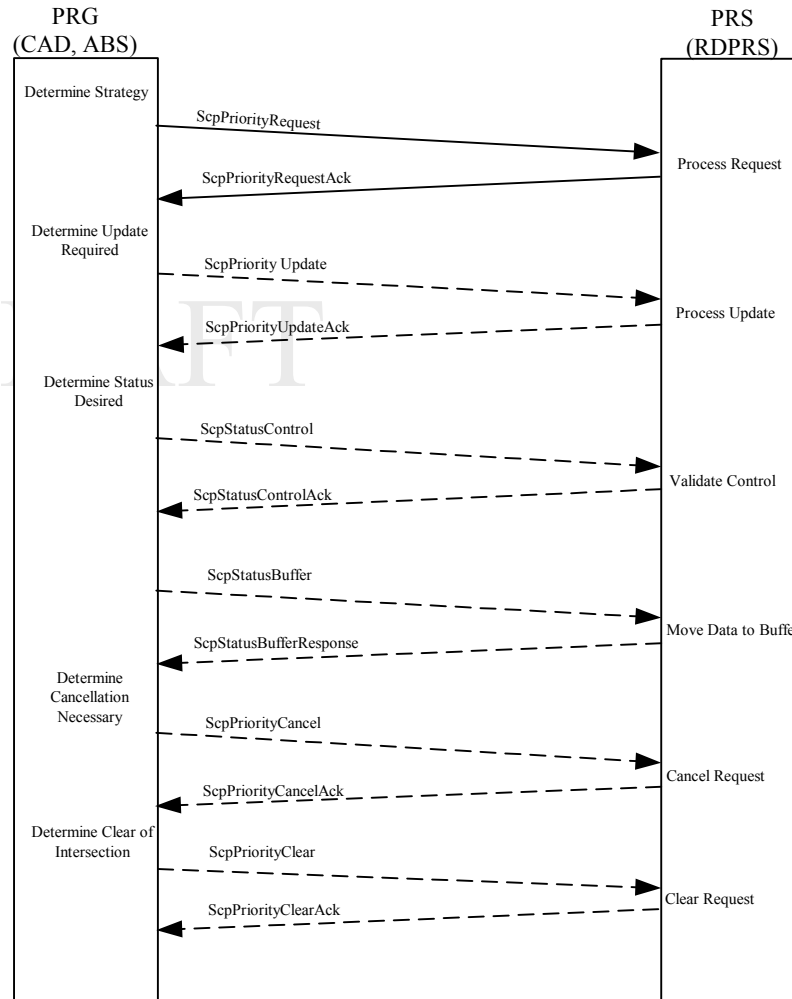
**Narrative:**

- 1) The PRG determines that the vehicle is approaching an SCP-equipped Scenario #2 intersection, and that the criteria are met to initiate a priority request. The PRG sends a ScpPriorityRequest message to the Priority Request Publisher (PRS).
  - a. The PRS validates the request and sends a ScpPriorityRequestAck to the PRG.
  - b. If the acknowledgement contains an error indication, the dialog ends, otherwise the PRG may optionally initiate any of items 2-5 below.
- 2) The PRG determines that it requires a status update on the priority request. The PRG sends a ScpStatusControl to the PRS.
  - a. The PRS validates the status control and returns a ScpStatusControlAck message to the PRG.
  - b. If the acknowledgement contains no error indication, the PRG sends a ScpStatusBuffer to the PRS.
  - c. The PRS fills the status buffer and returns it to the PRG as a ScpStatusBufferResponse message.
- 3) The PRG determines that the priority request needs to be changed as a result of changed arrival time at the intersection and/or changes to the criteria matching. The PRG sends a ScpPriorityUpdate message to the PRS. The PRS processes the update and sends a ScpPriorityUpdateAck message to the PRG.
- 4) The PRG determines that the priority request needs to be canceled as the vehicle is not progressing towards the stop bar as planned, or has deviated from its route, or the vehicle is taken out of service, or experiences another locally defined state change requiring a cancellation. The PRG sends a ScpPriorityCancel to the PRS. The PRS processes the cancellation and sends a ScpPriorityCancelAck to the PRG, and the dialog ends.

The PRG determines that the vehicle is clear of the intersection, and the intersection requires explicit clears. The PRG sends a ScpPriorityClear

message to the PRS. The PRS clears the request and sends a SepPriorityClearAck to the PRG and the dialog ends.

**Message Sequence Diagram Page 2**



Normal Execution of "SCP Priority Request Scenario 2" Dialog

DRAFT

<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> SCP Priority Request Scenario 2		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Signal Control & Prioritization		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
Sep Priority Request	2011	Request a priority strategy from the PRS.
SepPriorityRequestAck	2010	Acknowledge the priority request.
SepPriorityUpdate	2009	Request that a previous priority request be modified.
SepPriorityUpdateAck	2008	Acknowledge the priority update.
SepStatusControl	2007	Request the PRS to prepare to provide status for a previous priority request.
SepStatusControlAck	2006	Acknowledge the status control
SepStatusBuffer	2004	Provide a buffer to obtain a priority request status
SepStatusBufferResponse	2005	Return the status of the priority request to the PRG
SepPriorityCancel	2002	Request the PRS to cancel a previous priority request
SepPriorityCancelAck	2003	Acknowledge the priority cancellation
SepPriorityClear	2012	Request the PRS to clear a completed priority request
SepPriorityClearAck	2001	Acknowledge the priority clear.



**Notes:**

- 1) If the vehicle clears the intersection and the PRG is not configured to generate a priority clear to the PRS, the dialog ends from the PRG view point. The dialog ends from the PRS view point after a local timeout.
- 2) The criteria for determining when a priority update, status update, or priority cancel should be initiated are agency/vendor defined.

DRAFT

**Scp Priority Request Scenario 4 – Message Based****TCIP Dialog Definition Page 1**

**Dialog Name:** SCP Priority Request Scenario 4-Message Based

**Business Area:** TSP

**Dialog Pattern:** Signal Control & Prioritization

**Purpose:** This dialog defines the generation and processing of priority requests by an onboard vehicle Priority Request Generator (PRG), inside the PTVTSP entity with direct communication to the Priority Request Server (PRS) according to NTCIP 1211 Scenario #4.

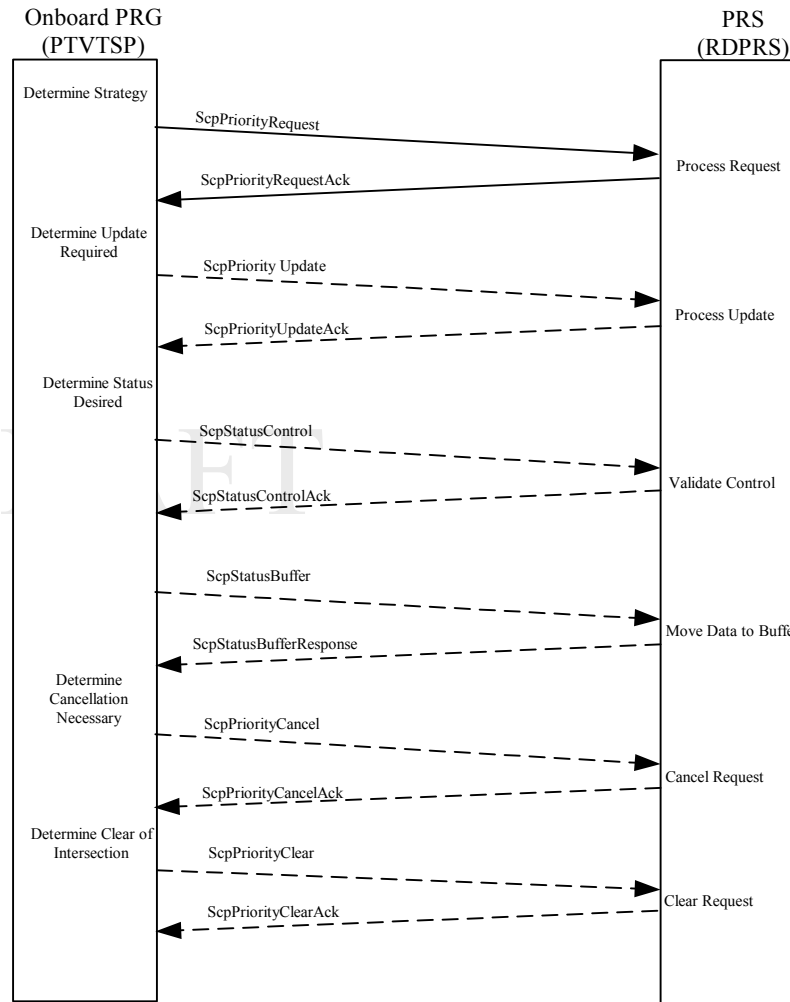
**Assumptions:**

- 1) PTVTSP has already received SCP data via the “Load TSP Business Rules” dialog.
- 2) PTVTSP has access to data resident in the vehicle logic unit (VLU) such as vehicle location, speed, bearing, schedule, and passenger count (if so equipped), or has subscriber to such data using the “Subscribe Onboard PRG Inputs” dialog.
- 3) The PRS may be Priority Request Publisher (RDPRS) (Roadside or TMC).

**Narrative:**

- 1) PTVTSP determines that the vehicle is approaching an SCP-equipped Scenario #4 intersection, and that the criteria are met to initiate a priority request. PTVTSP sends a ScpPriorityRequest message to the Priority Request Publisher (PRS).
  - a. The PRS validates the request and sends a ScpPriorityRequestAck to PTVTSP.
  - b. If the acknowledgement contains an error indication, the dialog ends, otherwise PTVTSP may optionally initiate any of items 2-5 below.
- 2) PTVTSP determines that it requires a status update on the priority request. PTVTSP sends a ScpStatusControl to the PRS.
  - a. The PRS validates the status control and returns a ScpStatusControlAck message to PTVTSP.
  - b. If the acknowledgement contains no error indication, PTVTSP sends a ScpStatusBuffer to the PRS.
  - c. The PRS fills the status buffer and returns it to PTVTSP as a ScpStatusBufferResponse message.
- 3) PTVTSP determines that the priority request needs to be changed as a result of changed arrival time at the intersection and/or changes to the criteria matching. PTVTSP sends a ScpPriorityUpdate message to the PRS. The PRS processes the update and sends a ScpPriorityUpdateAck message to PTVTSP.
- 4) PTVTSP determines that the priority request needs to be canceled as the vehicle is not progressing towards the stop bar as planned, or has deviated from its route, or the operator manually initiates a cancel (if so equipped), or the vehicle is taken out of service, or experiences another locally defined state change requiring a cancellation. PTVTSP sends a ScpPriorityCancel to the PRS. The PRS processes the cancellation and sends a ScpPriorityCancelAck to PTVTSP and the dialog ends.
- 5) PTVTSP determines that the vehicle is clear of the intersection, and the intersection requires explicit clears. PTVTSP sends a ScpPriorityClear message to the PRS. The PRS clears the request and sends a ScpPriorityClearAck to PTVTSP and the dialog ends.

**Message Sequence Diagram Page 3**



Normal Execution of "SCP Priority Request Scenario 4 - Message Based" Dialog

<b>TCIP Dialog Definition Page 4</b>		
<b>Dialog Name:</b> SCP Priority Request Scenario 4-Message Based		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Signal Control & Prioritization		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
Sep Priority Request	2011	Request a priority strategy from the PRS.
SepPriorityRequestAck	2010	Acknowledge the priority request.
SepPriorityUpdate	2009	Request that a previous priority request be modified.
SepPriorityUpdateAck	2008	Acknowledge the priority update.
SepStatusControl	2007	Request the PRS to prepare to provide status for a previous priority request.
SepStatusControlAck	2006	Acknowledge the status control
SepStatusBuffer	2004	Provide a buffer to obtain a priority request status
SepStatusBufferResponse	2005	Return the status of the priority request to the PRG
SepPriorityCancel	2002	Request the PRS to cancel a previous priority request
SepPriorityCancelAck	2003	Acknowledge the priority cancellation
SepPriorityClear	2012	Request the PRS to clear a completed priority request
SepPriorityClearAck	2001	Acknowledge the priority clear.

**Notes:**

- 1) If the vehicle clears the intersection and PTVTSP is not configured to generate a priority clear to the PRS, the dialog ends from PTVTSP view point, and ends from the PRS view point after a local timeout.
- 2) The criteria for determining when a priority update, status update, or priority cancel should be initiated are agency/vendor defined.

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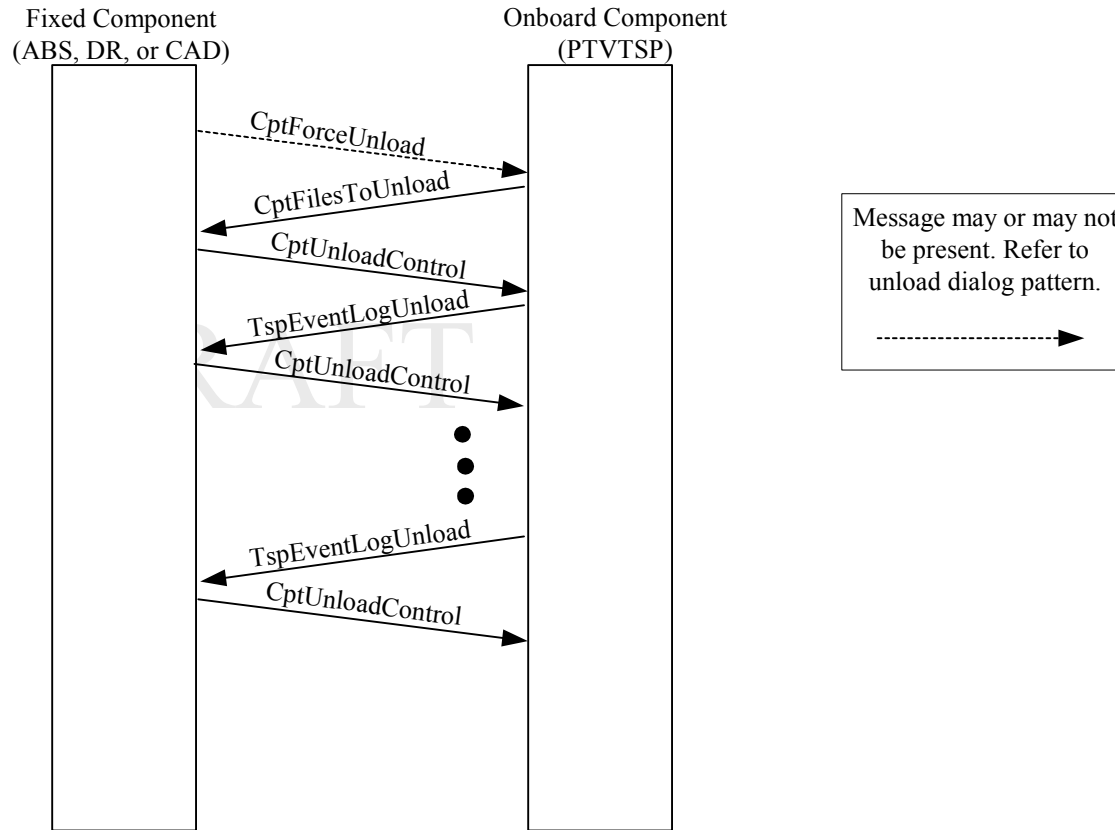
**Unload PRG Event Log****TCIP Dialog Definition Page 1****Dialog Name:** Unload PRG Event Log**Business Area:** TSP**Dialog Pattern:** Unload**Purpose:** Unload data on the history signal priority events from the PRG to the CAD/AVL system or a data repository.**Assumptions:**

1. The onboard component may be a PTVTSP.
2. The fixed component may be an Authorized Business System (ABS), Data Repository (DR), or a CAD/AVL System (CAD),

**Narrative:**

1. PTVTSP initiates the dialog based on a CptForceUnload message, or available files to unload combined with WLAN or ground network availability, and sends a CptFilesToUnload message.
2. CAD, DR, or ABS (fixed component) determines what files are available, needed, or eligible for deletion and sends a CptUnloadControl message to PTVTSP.
3. PTVTSP deletes any files specified for deletion.
4. If there is no file specified to unload the dialog ends. If the specified file is not available, PTVTSP sends a CptUnloadRequestError message and the dialog ends. If there is a file specified and it is available, PTVTSP sends the specified TSPEventLogUnload (file) to the CAD/AVL System or data repository.
5. The fixed component receives and validates the TSPEventLogUnload message and goes to step 2 above.

**Message Sequence Diagram Page 2**



Normal Execution of the "Unload PRG Event Log" Dialog.

<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> Unload PRG Event Log		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Unload		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
CptForceUnload	Cpt 2017	Trigger PRG to initiate a unload process. Primary use is to unload via a laptop instead of a wireless LAN.
CptUnloadControl	Cpt 2014	Used by fixed component to control the unload process.
CptUnloadRequestError	Cpt 2015	Used by PTVTSP to notify fixed component of a file request error.
TSPEventLogUnload	Tsp	Conveys Scp History data from PTVTSP to fixed component.
CptFilesToUnload	Cpt 2013	Identifies files stored in a PRG that are ready for unload to the corresponding Fixed component.
<b>Notes:</b>		



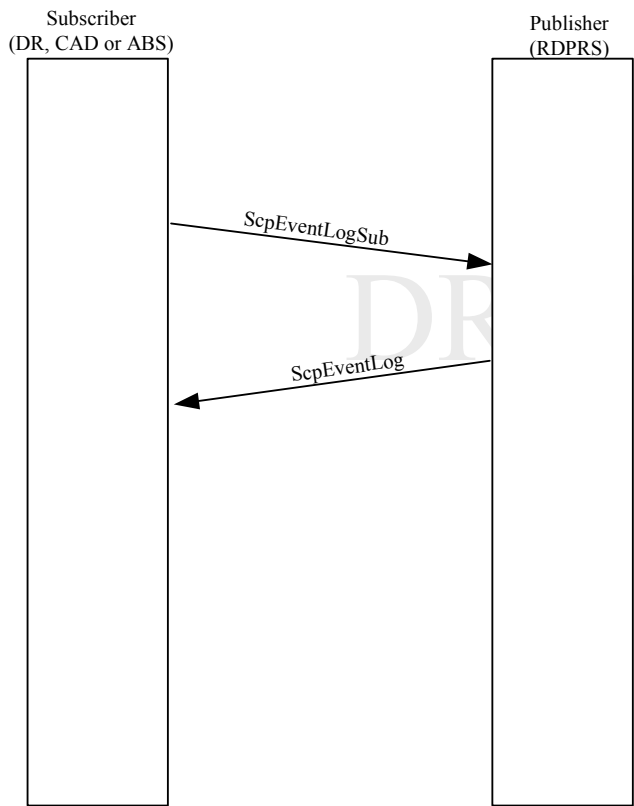
**Subscribe PRS Event Log****TCIP Dialog Definition Page 1****Dialog Name:** Subscribe PRS Event Log**Business Area:** TSP**Dialog Pattern:** Subscription**Purpose:** Provide a mechanism for a CAD/AVL System (CAD) or a transit Data Repository (DR) (subscriber) or other Authorized Business System (ABS) to obtain a historical record of signal priority events from a suitably equipped Traffic Management Center (publisher).**Assumptions:**

1. The subscription may be a query or periodic type.
2. The subscriber may be CAD, DR, or ABS.
3. The publisher is RDPRS (Roadside or TMC).

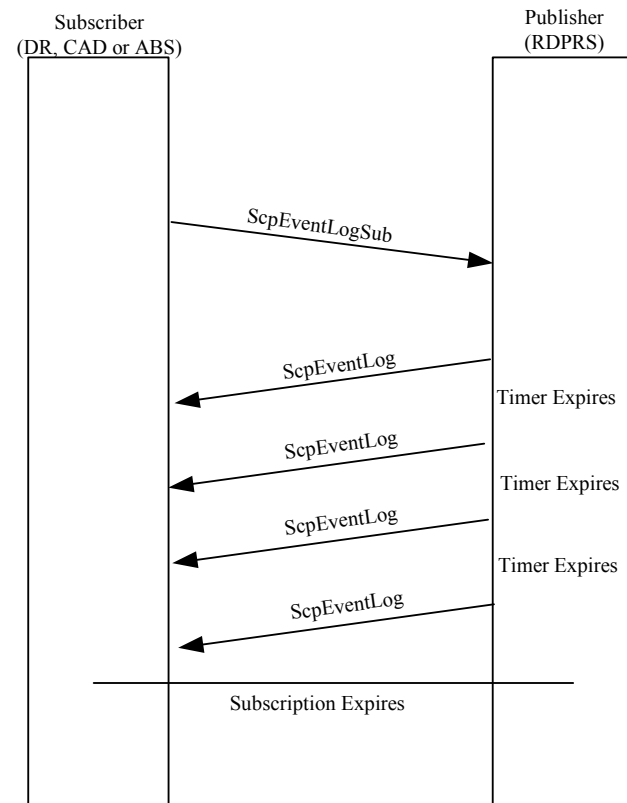
**Narrative:**

- 1) The subscriber determines the intersections of interest, and forwards a ScpHistoryDataSub message (subscription request) . If the subscription is an ongoing periodic subscription, the reporting interval and subscription duration are also specified in the subscription request.
- 2) The publisher validates the subscription request.
  - a. If the subscription request is invalid, the publisher sends a CptSubErrorNotice message to the subscriber and the dialog ends.
  - b. If the subscription request is a valid query, the publisher sends a ScpHistoryData message to the subscriber and the dialog ends.
  - a. If the subscription request is a valid periodic subscription request, the publisher sends a ScpHistoryData message to the subscriber, containing history data currently on hand, and sends new ScpHistoryData messages at the interval specified in the subscription request.
- 3) The periodic subscription ends when:
  - a. The subscription expires.
  - b. The subscriber sends a new HistoryDataSub message requesting a cancellation.
  - c. The publisher sends a CptSubErrorNotice to the subscriber.

**Message Sequence Diagram Page 2**



Normal Execution of the Query "Subscribe PRS Event Log" Query Subscription.



Normal Execution of the "Subscribe PRS Event Log" Periodic Subscription .

<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> Subscribe PRS Event Log		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Subscription		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
ScpEventLogSub	SCP 2015	Used by the subscriber to request signal priority history data from the publisher.
ScpEventLog	SCP 2014	Used by the publisher to provide signal priority history data to the subscriber.
CptSubErrorNotice	CPT 2000	Used by the publisher to notify the subscriber that the subscription is terminated with an error status.
<b>Notes:</b>		

**Subscribe CC PRG Inputs****TCIP Dialog Definition Page 1**

**Dialog Name:** Subscribe CC PRG Inputs

**Business Area:** TSP

**Dialog Pattern:** Subscription

**Purpose:** Provide information on transit vehicle approaches to signal priority-equipped intersections to the Traffic Management Center. This subscription is required for NTCIP 1211 Scenario #3 generation of priority requests by the Traffic Management Center-based PRG.

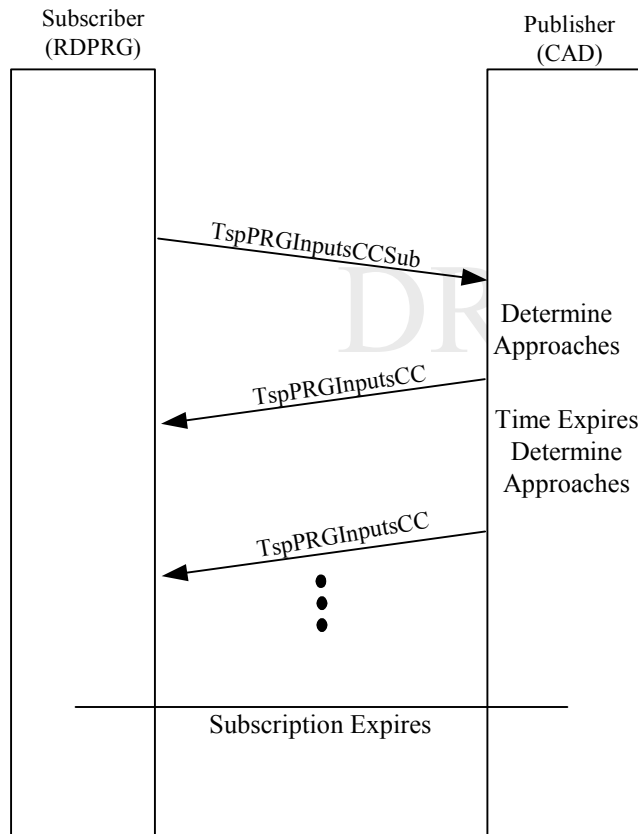
**Assumptions:**

1. The subscription may be of the event-driven or periodic type. Event-driven will result in more frequent, smaller messages to the TMC, while a periodic subscription would allow information to be buffered for several seconds and “batched” in a larger message.
2. The CAD/AVL System knows the locations of intersections, and stop bars as part of its configuration.
3. The publisher may be a CAD/AVL System (CAD),
4. The subscriber may be Priority Request Generator (RDPRG).

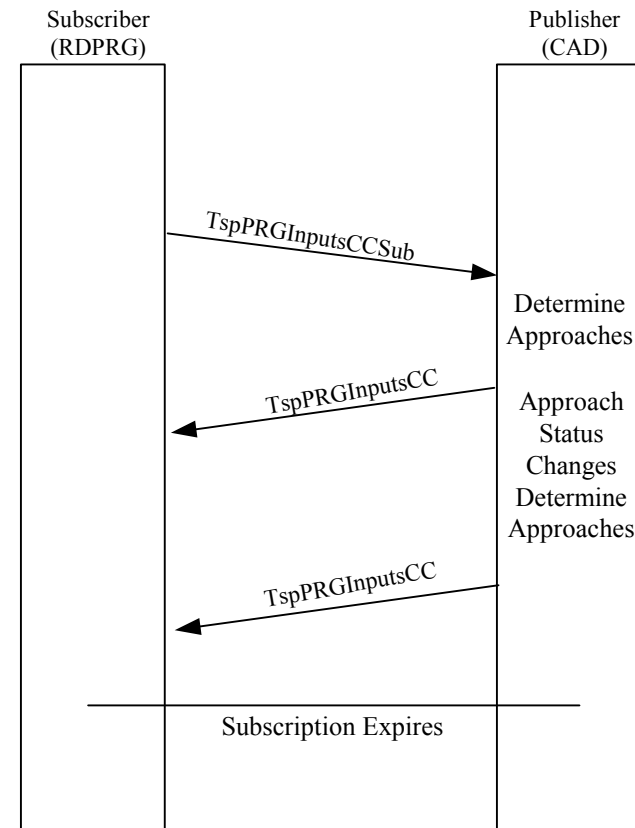
**Narrative:**

1. The subscriber sends a TspPRGInputsCCSub message to CAD.
2. CAD responds with a TspPRGInputsCC message containing current approach information.
  - a. If the subscription type is event, CAD waits for an approach to an SCP-equipped intersection, or abandonment of an approach to be detected and then reports it with a TspPRGInputsCC message.
  - b. If the subscription type is periodic, CAD waits for the time to expire and then sends a TspPRGInputsCC message.
3. The dialog ends when the subscriber sends a new TspPRGInputsSub message indicating “cancel”, or the subscription expires.

**Message Sequence Diagram Page 2**



Normal Execution of the "Subscribe CC PRG Inputs" Periodic Subscription



Normal Execution of the "Subscribe CC PRG Inputs" Event Subscription.

<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> Subscribe CC PRG Inputs		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Subscription		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
TspPRGInputsCCSub	Scp 2016	Used by the TMC or roadside PRG to establish the subscription and request the approach information for SCP-equipped intersections.
TspPRGInputsCC	Scp 2017	Provides the information on transit fleet vehicle approaches to SCP-equipped intersections.
<b>Notes:</b>		

**Subscribe Onboard PRG Inputs****TCIP Dialog Definition Page 1**

**Dialog Name:** Subscribe Onboard PRG Inputs

**Business Area:** TSP

**Dialog Pattern:** Subscription-Periodic

**Purpose:** This dialog allows an onboard Signal Priority Request Generator (PRG) external to the Vehicle Logic Unit (VLU), to obtain real-time vehicle status information necessary to generate situation-appropriate signal priority requests.

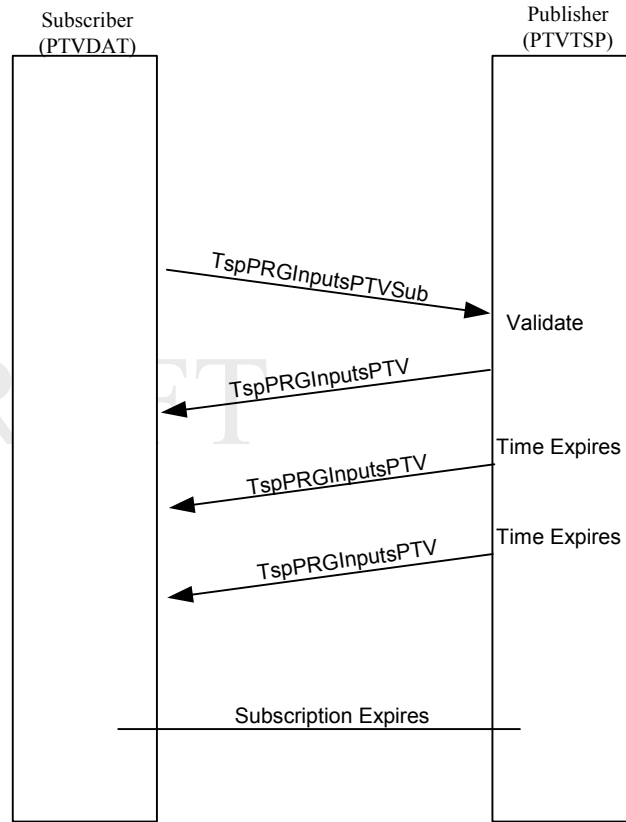
**Assumptions:**

1. The PRG separately has obtained the necessary contextual information (intersections, strategies, schedules, boundaries) via the “Load TSP Business Rules” dialog.
2. If the PRG operates within the VLU, the data transfer is internal and this dialog is not required.
3. The publisher may be PTV Manage VLU Data (PTV DAT).
4. The subscriber may be PTV Manage Transit Signal Priority (PTV TSP).

**Narrative:**

1. PTV TSP (subscriber) sends a TspPRGInputsPTVSub message to PTV DAT (publisher).
2. The publisher validates the TspPRGInputsPTVSub message and:
  - a. If the message is invalid, sends a CptSubErrorNotice to the subscriber and the dialog ends.
  - b. If the message is valid, the VLU sends a TspPRGInputsPTV message to the subscriber.
3. The publisher waits for the periodic interval to expire and sends a TspPRGInputsPTV message.
4. The dialog ends when the subscription expires, is cancelled by the subscriber, or the is shutdown.

**Message Sequence Diagram Page 2**



Normal Execution of the "Subscribe Onboard PRG Inputs" Dialog



<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> Subscribe Onboard PRG Inputs		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Subscription Periodic		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
TspPRGInputsPTVSub	2019	Request a subscription to PRG inputs.
TspPRGInputsPTV	2018	Provide real-time PRG input information.
CptSubErrorNotice	2000	Report an error with the PRG input subscription.
<b>Notes:</b>		

**SCP Priority Request Scenario 4 – Optical Based****TCIP Dialog Definition Page 1**

**Dialog Name:** SCP Priority Request Scenario 4 – Optical Based

**Business Area:** TSP

**Dialog Pattern:** Signal Control & Prioritization

**Purpose:** This dialog defines the generation and processing of priority requests by an onboard vehicle Priority Request Generator (PRG), inside the PTVTSP entity with direct communication to the Priority Request Publisher (PRS) using an optical emitter on the PTV.

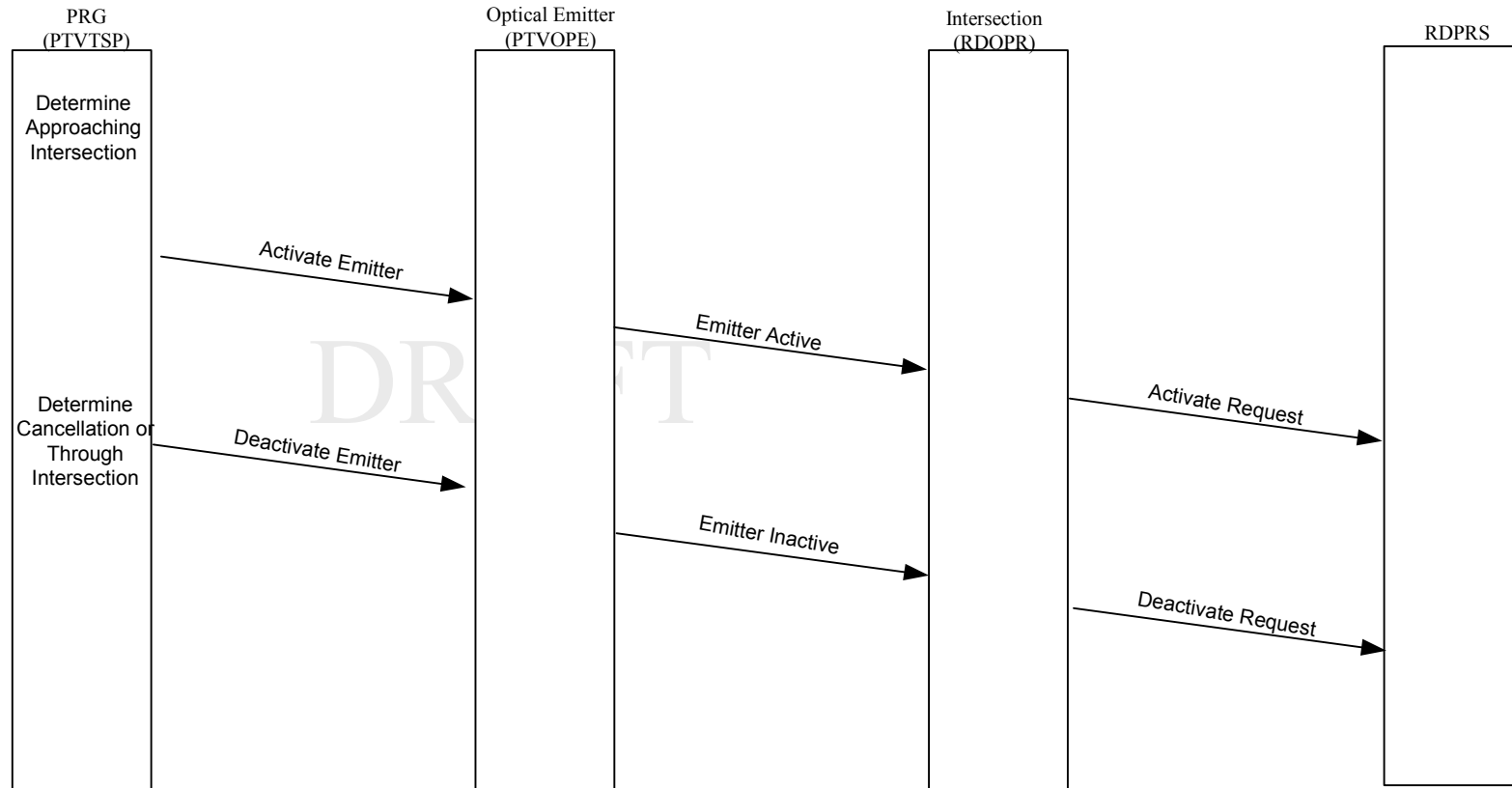
**Assumptions:**

1. PTVTSP has already received data via the “Load TSP Business Rules” dialog.
2. PTVTSP has access to data resident in the Vehicle Logic Unit (VLU) such as vehicle location, speed, bearing, schedule, and passenger count (if so equipped), or has subscribed to such data using the “Subscribe Onboard PRG Inputs” dialog.

**Narrative:**

1. PTVTSP determines that the vehicle is approaching an SCP-equipped Scenario #4 intersection, and that the criteria are met to initiate a priority request. PTVTSP send a priority activation request (PID=500) to the emitter via the Vehicle Area Network (VAN).
2. The optical emitter receives and processes the message. If the emitter is unable to process the request, the emitter responds with an error message (PID=500) via the VAN, and the dialog ends.
3. PTVTSP determines that the request needs to be cancelled, or the vehicle has cleared the intersection. PTVTSP sends a priority deactivation request (PID=500) to the emitter via the VAN.

**Message Sequence Diagram Page 2**



Normal Execution of the "SCP Priority Request Scenario 4 - Optical Based" Dialog

<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> SCP Priority Request Scenario 4 – Optical Based		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Signal Control & Prioritization		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
IntersectionStatus Pre-emption and Configuration	SAE J1587 PID=500	This message conveys all signal priority information between the VLU and the optical emitter.
DRAFT		
<b>Notes:</b>		

**Signal Priority Request Scenario 5****TCIP Dialog Definition Page 1**

**Dialog Name:** Signal Priority Request Scenario 5

**Business Area:** TSP

**Dialog Pattern:** Blind Notification

**Purpose:** Send a notification to a Scenario #5 equipped intersection of a PTV approach.

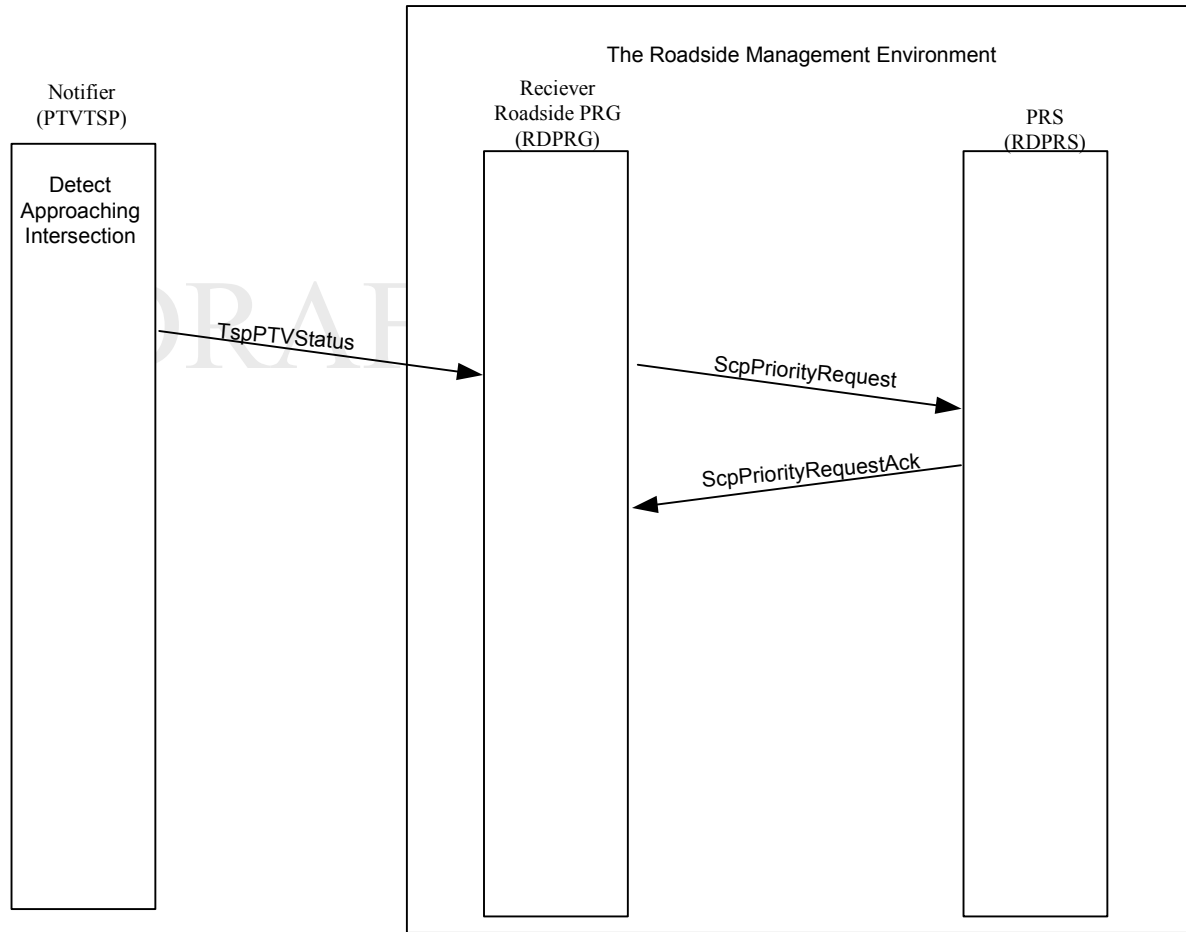
**Assumptions:**

1. PTVTSP has previously received information about the scenario 5 equipped intersection via the Load TSP Business Rules dialog.

**Narrative:**

1. PTVTSP determines that the PTV is approaching a scenario 5 equipped intersection.
2. PTVTSP sends a TspPTVStatus message to the roadside PRG (RDPRG). From the VLU perspective the dialog ends.
3. RDPRG receives the TspPTV Status message and determines whether a priority request is appropriate.
  - a. If a request is not deemed appropriate the dialog ends.
  - b. If a request is appropriate, the PRG initiates a ScpPriorityRequest/ScpPriorityRequestAck exchange with the PRS.

**Message Sequence Diagram Page 2**



Normal Execution of the "Signal Priority Request 5" Dialog

<b>TCIP Dialog Definition Page 3</b>		
<b>Dialog Name:</b> Signal Priority Request Scenario 5		
<b>Business Area:</b> TSP		
<b>Dialog Pattern:</b> Blind Notification		
<b>Message Name</b>	<b>Message Identifier</b>	<b>Role</b>
TspPTVStatus	TSP 2021	Notify a scenario 5 equipped intersection of a PTV approach.
DRAFT		
<b>Notes:</b>		